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2	Inducers of Motion Sickness in Vehicles: A Systematic Review of Experimental
3	Evidence and Meta-Analysis
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20 Highlights

- We conducted a systematic literature review of motion sickness inducers.
- We identified eight categories of motion sickness inducers in vehicles.
- A meta-analysis was conducted to assess the influence of motion cues.
- Research gaps and future research directions have been pointed out.

25 Abstract

26 With the development of intelligent cabins and the popularity of smart 27 devices, motion sickness has become an increasing concern. A number of theories 28 have been proposed to explain the cause of motion sickness in vehicles. However, 29 because of the diversity of the dynamical characteristics, road conditions, and in-30 vehicle human-machine interaction designs, the influence of the inducers on motion 31 sickness in vehicles has not yet been fully quantified. Thus, in this paper, we aim to 32 review and summarize the influential factors of motion sickness in road vehicles 33 through a systematic review. In total, we identified 57 studies related to influential 34 factors of motion sickness in vehicles, of which, 27 were further included for meta-35 analysis. In total, we identified eight categories of motion sickness inducers in 36 vehicles, including the type of eye view, non-driving-related task availability, existence of artificial motion cues, head dynamic movement, vehicle dynamics, 37 38 internal layout of vehicle, individual differences, and others. Most inducers had 39 consistent effects on inducing motion sickness; however, inconsistent results have 40 also been observed in vehicle dynamics, head dynamic movement, eye view, 41 individual difference, and artificial motion cues (i.e., cues regarding the motion states 42 of the ego-vehicle provided through in-vehicle auditory, tactile, or visual interfaces). 43 Additional meta-analysis was conducted for motion cues. It was found that only 44 natural present motion cues (i.e., cues regarding relative movement between the ego-45 vehicle and the environment through the windshield or side windows) and non-visual 46 artificial anticipatory motion cues (i.e., auditory or tactile artificial motion cues

47 regarding the future motion of ego-vehicle) were effective in alleviating motion
48 sickness. Future research directions have been pointed out. Our study can provide
49 insights into the optimization of vehicle design to mitigate motion sickness among
50 occupants.

51 Keywords: motion sickness; experimental evidence; meta-analysis; systematic
52 literature review

53 1. Introduction

54 The intellectualization of the vehicle cabin has become a tendency in the past 55 few years. With the development of microelectronics and communication 56 technologies, an increasing number of infotainment functions (e.g., video streaming in 57 Polestar, Golson, 2021) have become available in vehicles. Even in vehicles without 58 infotainment systems, passengers also tend to spend their commute time on 59 smartphones or tablets (Hamadneh & Esztergár-Kiss, 2022). These technologies can 60 improve the ride experience in vehicles and also bring tremendous economic benefits. 61 For example, according to a recent report, the average commuting time among the 42 62 biggest cities in China is as high as 72 minutes (Chen, 2021). The commuting time, if 63 being utilized for work, can significantly promote social efficiency. However, 64 although the intellectualization of vehicle is of economic and social value, the public 65 still have concerns about the smart cabin and the motion sickness (or carsickness) in vehicles is one of them. 66

Motion sickness has been widely studied in past decades, in not just vehicular
areas, but also aviation (e.g., Turner et al., 2000), rail transit (e.g., Suzuki et al., 2005),

69	and human-machine interface (HMI) domain, such as virtual reality (e.g., Chang et
70	al., 2020). Motion sickness is usually defined as a kind of physical discomfort caused
71	by passive movement of the human body. The typical symptoms of motion sickness
72	include malaise, nausea, and even emesis (Smyth et al., 2021). Further, some previous
73	research has pointed out that compared to drivers, motion sickness is more likely to
74	occur among passengers (Rolnick & Lubow, 1991), especially when they engage in
75	non-driving-related visual tasks such as reading texts and watching videos (Turner &
76	Griffin, 1999a). For highly susceptible occupants, motion sickness might occur even
77	without engaging in visual tasks. Obviously, motion sickness would impair the user
78	experience and decrease the public acceptance of intelligent cabins in vehicles.
79	Motion sickness could be predicted based on a mathematical model. For
80	example, motion sickness does value (MSDV), as an objective mathematical
81	approach, was used to quantify the motion sickness induced by vehicle dynamics
82	(Saruchi et al., 2021). However, although the methods of mathematical models can be
83	used to predict motion sickness based on vehicle dynamics or head dynamic
84	movement, they fail to consider the individual differences and the impact of context
85	information (e.g., visual cues). For example, previous research has identified an
86	inconsistency between mathematical estimation and subjective rating (Saruchi et al.,
87	2021). At the same time, physiological signals (e.g. electrocardiogram (ECG), facial
88	skin temperature, and body movement) can also be used to evaluate motion sickness
89	(Keshavarz et al., 2022; Wibirama et al., 2018). For example, Keshavarz et al. (2022)
90	found that changes in facial skin temperature and body movement were the strong

91	indicators of visually induced motion sickness (VIMS) and Wibirama et al. (2018)
92	found that heart rate variability measured by ECG was a reliable indicator of VIMS.
93	However, there is still no standard way of quantifying motion sickness using
94	physiological signals as the accuracies of physiological measurement vary across
95	studies. This might be because physiological responses are highly susceptible to
96	environmental conditions (e.g., the GSR is associated with cabin temperature,
97	Maulsby & Edelberg, 1960) and even cognitive states of participants (e.g., the heart
98	rate increases with increased workload, Meshkati, 1988). Further, participants might
99	be able to self-adapt to inducers of motion sickness (Keshavarz et al., 2022; Smyth et
100	al., 2021), nullifying the effectiveness of physiological signals as measures of motion
101	sickness. From this perspective of view, the subjective ratings might be a more
102	reliable measure of motion sickness. For example, the questionnaire methods, such as
103	the motion sickness assessment questionnaire (MSAQ), MIsery SCale (MISC), fast
104	motion sickness scale (FMS), and simulator sickness questionnaire (SSQ) have been
105	used in numerous studies for the subjective rating of motion sickness (Saruchi et al.,
106	2021).



113	related inducers (e.g., low frequency of vertical oscillation, low frequency of fore-
114	and-aft oscillation, low frequency of lateral oscillation and high lateral acceleration
115	resulted from steering's angle). In order to better explain the causes of motion
116	sickness in vehicles, multiple theories have been proposed. For example, the theory of
117	sensory conflict (Reason & Brand, 1975) attributes the cause of motion sickness to the
118	mismatch of vestibular signals, visual signals, and somatosensory motion cues.
119	Specifically, occupants in a vehicle can visually perceive the movement of the body
120	relative to the environment while the somatosensory motion cues indicate that the
121	body is stationary. These contradictory signals can lead to motion sickness. Thus,
122	providing information regarding the motion states of the ego-vehicle (i.e., motion
123	cues) that are consistent with the vestibular signals may alleviate motion sickness
124	(Yusof et al. 2020). It should be noted that the motion cues can be both artificial
125	motion cues (i.e., cues provided through in-vehicle auditory, tactile, or visual
126	interfaces) and natural motion cues (i.e., cues regarding relative movement between
127	the ego-vehicle and the environment through the windshield or side windows). As
128	another explanation, the theory of postural instability (Riccio & Stoffregen, 1991)
129	states that the occupants' decreased control ability of their bodies in movement can
130	lead to motion sickness, which is the case for passengers in vehicles. Further, the
131	weak motion anticipation of ego-motion among passengers in vehicles has been used
132	to explain the higher susceptibility of motion sickness among passengers compared to
133	that of drivers (Golding & Gresty, 2005).

134 However, previous research rarely compared the influence of different 135 inducers or theories, which is a major research gap at the current stage, given that 136 motion sickness in vehicles may be attributed to multiple inducers simultaneously 137 (Schmidt et al., 2020) in certain situations and different inducers may contribute differently to motion sickness. Thus, in order to better guide the design of the in-138 139 vehicle HMIs and vehicle control algorithms, it is necessary to thoroughly review the 140 literature that targets inducers of motion sickness in vehicles and quantitatively assess 141 the effects of these inducers. Being different from existing review articles on motion 142 sickness (e.g., Saruchi et al., 2021) that focused on the causes, measurements, and 143 solutions of motion sickness in autonomous vehicles, the scope of our study targeted 144 the experimental evidence of motion sickness inducers in vehicles (either controlled 145 by human drivers or driving automation). Considering the potential issues of 146 physiological measures and mathematical models, we adopted subjective measures as 147 the metrics of motion sickness. Specifically, only the experiments using subjective 148 ratings as the measure of motion sickness were included in the literature review and 149 meta-analysis.

150 **2.** Methods

151 2.1. Data Sources and Search

Targeting articles providing experimental evidence on the effects of potential inducers on motion sickness, we elicited the keywords according to the causes of the motion sickness mentioned in previous research. Specifically, as shown in Figure 1, "motion sickness" and "vehicle" (or their synonyms) were mandatory. Then, one of the words related to the inducers of motion sickness (or their synonyms and
equivalences) was combined with these two mandatory keywords in the search. Four
databases were searched, including Scopus, PubMed, Web of Science, and IEEE
Xplore. No temporal restrictions were set. Searches were first conducted on 15th
October 2022 and were updated on 15th August 2023. Finally, 626 studies were
identified from the search, of which the time span was from the year 1959 to 2023.



Figure 1. Keywords used for searching

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163 164

166 2.2. Inclusion Criteria

As the aim of our study is to review the experimental evidence of motion sickness in vehicles and quantify the inducers, the following criteria were set to further screen the identified literature from keyword search, i.e., the studies should: - Contain experiments on motion sickness in vehicles (either in a simulated environment or real vehicles on the road). This is because biased responses might be collected using a survey alone (it is difficult to recall the severity of motion sickness accurately if not reported immediately after experiencing it). Further, pure

174	medical, biological, or genetic studies cannot directly provide experimental
175	evidence on the influential factors of motion sickness in vehicles.
176	- Investigate the influential factors of motion sickness in vehicles and all influential
177	factors must reflect an attribute within a real vehicular/road context, because the
178	motion-sickness-related findings in other transportation methods (e.g., train, ship,
179	and aircraft) may not be directly transferable to motion sickness in vehicles.
180	- Evaluate the severity of motion sickness using subjective measures, as the
181	physiological measurement or mathematical estimation alone may be less reliable
182	compared to subjective measurement.
183	- Include at least one continuous or multi-level influential factor of motion sickness
184	as the independent variable and the subjective rating of motion sickness as the
185	dependent variable.
186	Guided by the above-mentioned criteria, we examined the title and abstract of
187	the identified literature followed by full-text screening. It is noteworthy that, the
188	experimental procedures ought to be executed either within actual vehicles or using
189	driving simulators (i.e. simulators with cabin environment). In cases where the
190	experiments are carried out utilizing alternative simulators (e.g., oscillator, sled) or
191	virtual reality (VR) platforms, it is imperative that the identified influential factors can
191 192	virtual reality (VR) platforms, it is imperative that the identified influential factors can be transferred to real vehicles. Thus, for the studies where dynamic characteristics of
191 192 193	virtual reality (VR) platforms, it is imperative that the identified influential factors can be transferred to real vehicles. Thus, for the studies where dynamic characteristics of the simulators were used as independent variables, the dynamic characteristics of
191 192 193 194	 virtual reality (VR) platforms, it is imperative that the identified influential factors can be transferred to real vehicles. Thus, for the studies where dynamic characteristics of the simulators were used as independent variables, the dynamic characteristics of these simulators must align with the parameters intrinsic to vehicular dynamics, with

196 Newman, 2004), and longitudinal and lateral accelerations under 4 m/s² (Bosetti et al.,





Figure 2. PRISMA Framework for paper selection



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201 The framework of PRISMA (Preferred Reporting Items for Systematic 202 Reviews and Meta-analysis) was followed during the whole screening process (Figure 203 2). Two reviewers independently selected the papers following the same procedures. 204 In case of conflicts, two reviewers would negotiate to reach a consensus. Finally, 57 205 papers were included for qualitative analysis (see Table 1) and 27 papers were used

206 for meta-analysis.

207 It should be noted that we considered studies that targeted both drivers and 208 passengers in both vehicles controlled by human drivers or driving automation. In the 209 study, if occupants were required to be responsible for driving safety, then they were 210 considered as drivers (4 out of 57 studies); Otherwise, they were considered as

211 passengers (56 out of 57).

Reference	Category of motion cues	Treatment	Experimental environment	Subjective Measurement
Pöhlmann et al., 2022	Others	Partial FOV vs. Full FOV	Virtual reality + rotating chair	MISC
Suwa et al., 2022	Artificial motion cues	Present motion cues (w/ vs. w/o)	Fixed-base simulator (with vertical vibration)	MSSQ/MISC
Sato et al., 2022	Internal layout	Head-fixed vs. earth-fixed coordinate	Fixed-base simulator (with vertical vibration)	MSSQ/MISC
Irmak et al., 2022	Vehicle dynamic	Oscillation (amplitude)	Oscillator (fore-aft)	MSSQs/MISC
Bohrmann et al., 2022	Eye View	Internal vs. external view	Instrumented car	FMS/MSAQ/MSSQ
	Artificial motion cues	Present motion cues with LED (w/ vs. w/o)	—	
Karjanto et al., 2022	Vehicle dynamic	Driving style (conservative vs. aggressive)	Instrumented car	MSSQ/MSAQ
Li et al., 2022	Eye View	Blindfolded vs. internal vs. external view	6-DoF Simulator	NSQ (points scale
	Others	Predictability (non- vs. predictable)	_	unknown)
Yunus et al., 2022	Vehicle dynamic	MSDV	Instrumented car	MSSQs/SR
Li & Chen, 2022	Artificial motion cues	Anticipatory motion cues (w/ vs. w/o)	6-DoF Simulator	MSSQs/MISC
Brietzke et al., 2021a	Eye View	Internal vs. external view	Instrumented car	MSSQs/NSQ (11-
	Vehicle dynamic	MSDV	—	points)
	Individual difference	Susceptibility to motion sickness	—	
Hainich et al., 2021	Artificial motion cues	Anticipatory motion cues (w/ vs. w/o)	Instrumented car	MSSQ/SSQ
	Individual difference	Susceptibility to motion sickness	—	
Irmak et al., 2021	Eye View	Internal vs. external view	Instrumented car	MSSQ/MISC
Maculewicz et al., 2021	Artificial motion cues	Anticipatory motion cues (w/ vs. w/o)	Instrumented car	MSSQ/MISC
de Winkel et al., 2021	Artificial motion cues	Present motion cues (w/ vs. w/o)	Virtual reality + Hexapod motion simulator	MSSQ/FMS
	Artificial motion cues	Anticipatory motion cues (w/ vs. w/o)		

Table 1. A summarization of qualified literature (the definitions of the *Category of Motion Cues* and *Treatment* can be found in section 3.1)

Zhao et al., 2019	Others	Predictability (non- vs. predictable)	6-DoF Simulator	SSQ
Kuiper et al., 2020a	Others	Predictability (non- vs. predictable)	Sled	MISC/MSSQ
Kuiper et al., 2020	Artificial motion cues	Anticipatory motion cues (w/ vs. w/o)	Sled	MISC/MSSQ
Mu et al., 2020	Artificial motion cues	Present motion cues (w/ vs. w/o)	Instrumented car	MISC
	Artificial motion cues	Anticipatory motion cues (w/ vs. w/o)	-	
Kuiper et al., 2019	Vehicle dynamic	Oscillation (frequency)	6-DoF Simulator	MSSQ/MISC
Meschtscherjakov et al., 2019	Artificial motion cues	Present motion cues (w/ vs. w/o)	Instrumented car	MSSQs/MSAQ
Ihemedu-Steinke et al., 2018	Artificial motion cues	Present motion cues (w/ vs. w/o)	Virtual reality + 2-DoF simulator	SSQ
Hanau & Popescu, 2017	Artificial motion cues	Present motion cues (w/ vs. w/o)	Bus	MSAQ
Karjanto et al., 2017	Artificial motion cues	Anticipatory motion cues (w/ vs. w/o)	Instrumented car	MSAQ/MSSQ
McGill et al., 2017	Artificial motion cues	Present motion cues (w/ vs. w/o)	Virtual reality + instrumented car	SSQ/MSSQs
Fujita & Nakanishi, 2017	Internal layout	Window shape	Monitor	SSQ
Miksch et al., 2016	Artificial motion cues	Present motion cues (w/ vs. w/o)	Instrumented car	SSQ
Wada & Yoshida, 2016	Eye View	Blindfolded vs. external view	Instrumented car	MSSQ/SR
	Head dynamic movement	Tilt in cornering	_	
Isu et al., 2014	NDRT availability	No NDRT vs. NDRT	Instrumented car	MSSQ/NSQ (11-points)
Wada et al., 2012	Head dynamic movement	Tilt in cornering	Instrumented car	SR
Butler & Griffin, 2009	Eye View	Blindfolded vs. internal vs. external view	Oscillator (fore-aft, pitch)	Adapted-SR
	Vehicle dynamic	Phase difference (pitch and fore-aft oscillation)	-	
Morimoto et al., 2008a	NDRT availability	No NDRT vs. NDRT	Instrumented car	NSQ (11-points)
Morimoto et al., 2008b	NDRT availability	No NDRT vs. NDRT	Instrumented car	NSQ (11-points)
	Artificial motion cues	Present motion cues (w/ vs. w/o)	-	
Kato & Kitazaki, 2008	Artificial motion cues	Present motion cues (w/ vs. w/o)	Instrumented car	Adapted-SR

Kato & Kitazaki, 2006b	Eye View	Blindfolded vs. internal vs. external view	Instrumented car	Adapted-SR
	Artificial motion cues	Present motion cues (w/ vs. w/o)	_	
Kato & Kitazaki, 2006a	Vehicle dynamic	MSDV	Instrumented car	Adapted-SR
Lin et al., 2005	Artificial motion cues	Anticipatory motion cues (w/ vs. w/o)	Simulator (DoF unknown)	RSSQ
Golding et al., 2001	Vehicle dynamic	Oscillation (frequency)	Instrumented car	MSSQ/SR
Turner & Griffin, 1999b	Vehicle dynamic	MSDV	Bus	IR
Golding et al., 1997	Vehicle dynamic	Oscillation (frequency)	Oscillator (fore-aft)	MSSQ/SR
Probst et al., 1982	Eye View	Blindfolded vs. internal vs. external view	Instrumented car	NSQ (11-points)
Vogel et al., 1982	Others	Seated position (e.g., sitting upright facing forward)	Ambulance car	NSQ (217 points)
Brietzke et al., 2021b	Artificial motion cues	Present motion cues (w/ vs. w/o)	Instrumented car	MSSQs/NSQ (11- points)
	Head dynamic movement	Alignment with gravity-inertial force	_	F)
Cho & Kim, 2022	Eye View	Internal vs. external view	Virtual reality + Instrumented car	SSQ
	NDRT availability	No NDRT vs. NDRT	_	
	Artificial motion cues	Present motion cues (w/ vs. w/o)	_	
Jones et al., 2019	NDRT availability	No NDRT vs. NDRT	Instrumented car	NSQ (11 points)
	Vehicle dynamic	Driving style (absolute value of acceleration)	_	
	Individual difference	Susceptibility to motion sickness	_	
	Individual difference	Age	_	
DiZio et al., 2018	Vehicle dynamic	Oscillation (frequency)	Instrumented car	NSQ (11 points)
Sugiura et al., 2019	Head dynamic movement	Alignment with gravito-inertial force	Instrumented car	MSSQ/SR
Golding et al., 2003	Head dynamic movement	Alignment with gravito-inertial force	Instrumented car	MSSQ/SR
Wang et al., 2021	Vehicle dynamic	The absolute value of acceleration	Bus	NSQ (5 points)

Yusof et al., 2020	Artificial motion cues	Anticipatory motion cues (w/ vs. w/o)	Instrumented car	MSSQ/MSAQ
Kaplan et al., 2017	Individual difference	Sleep deprivation (4 h vs. 8h)	Oscillator	NSQ (10 points)
Karjanto et al., 2018	Artificial motion cues	Anticipatory motion cues (w/ vs. w/o)	Instrumented car	MSSQ/MSAQ
Jurisch et al., 2020	Vehicle dynamic	The absolute value of acceleration	8-DoF Simulator	MSSQ/MSQ
Salter et al., 2019	Internal layout	Cabin length (short vs. long)	Instrumented car	SSQ/MSSQs
	Internal layout	Direction of seat (0°vs. 10°)		
Kuiper et al., 2018	Internal layout	Display position (high vs. low)	Instrumented car	MISC
Schartmüller & Riener, 2020	Others	No scents vs. Scents (ginger, lavander)	Instrumented car	SSQ
Wijlens et al., 2022	Vehicle dynamic	The absolute value of acceleration	6-DoF Simulator	MSSQs/MISC
Reuten et al., 2023	Artificial motion cues	Anticipatory motion cues (w/ vs. w/o)	Sled	MSSQs/MISC

213 Note: DoF stands for Degrees of Freedom; SR stands for the Sickness Rating (a 6-point motion sickness rating scale, Golding et al. 2003); Adapted-SR stands for the 6-point

214 motion sickness rating scale adapted from SR, Kato and Kitazaki, 2006a; IR stands for Illness Rating (a 4-points motion sickness rating scale, Lawther & Griffin, 1986);

215 RSSQ stands for the Revised Simulator Sickness Questionnaire; MSQ stands for Motion Sickness Questionnaire (a 78-points motion sickness rating scale, Kennedy et al.,

216 1993); NSQ (n-points) stands for none standardized questionnaires with n number of levels. For all measures of motion sickness, the larger the scale, the more severe the

217 motion sickness. In this table and the following tables, vs. standards for versus, w/ stands for with, and w/o stands for without.

218 2.3. Meta-analysis

As some inconsistent evidence has been identified in the process of systematic literature review, we further applied the method of meta-analysis to quantify the influence of some potential motion sickness inducers. By integrating the information from relevant studies, meta-analysis could provide a more holistic picture regarding the influence of the potential inducers.

224 The dependent variable in the meta-analysis was the severity of motion 225 sickness measured by subjective ratings. Different subjective ratings were used in the 226 identified literature, with MSAQ, SSQ, and MISC being the most popular ones. Thus, 227 for the meta-analysis, we adopted the standardized mean difference (SMD, i.e., the 228 difference in mean outcome between groups over the standard deviation of outcome 229 among participants) as the effect size (Higgins & Green, 2008), with the bias removed 230 following Hedges'g (Harrer et al., 2021). It should be noted that if multiple measures 231 were taken in a study, we took the first measure after the administration of motion 232 stimuli for our meta-analysis. The independent variables in the meta-analysis were the 233 presence (versus absence) of the inducers. 234 The sample size N (i.e., number of trials) and the mean value and standard 235 deviation (SD) of the dependent variables were extracted from the literature directly if available; if only SD was not available, we followed one of the following three 236 237 equations from the Cochrane handbook (Higgins & Green, 2008) to estimate SD.

 $SD = SE \times \sqrt{N}$ (1)

239 $SD = \sqrt{N} \times (upper limit - lower limit) / tinv (1 - 0.95, N - 1)$ (2)

240

SD = width of IQR / 1.35

241	Where SE was the standard error of the effect size; CI was the 95% confidence
242	interval; IQR was the interquartile range; and tinv returns the t-value corresponding
243	with the two-tailed probability. It is worth mentioning that the adoption of equation
244	(3) was based on the assumption of a normal distribution of the experimental data. In
245	case the distribution of data was not provided, we assumed the normal distribution of
246	the experimental data if the parameter test with the requirement of normal distribution
247	(e.g., t-test) was used in the paper. If none of the above equations worked, we
248	contacted the authors to acquire the SD. If the author did not respond, but the mean
249	was available, we estimated the SDs through a multiple linear regression approach,
250	with the normalized SD as the dependent variable and the normalized mean of the
251	motion sickness severity, the type of cues (natural present motion cues vs. artificial
252	present visual motion cues vs. artificial anticipatory visual motion cues vs. artificial
253	non-visual anticipatory motion cues vs. cue absent), the exposure time and the
254	experimental environment (vehicle vs. simulator) as independent variables (see
255	Section 3.2 for definitions of the levels). For the model selection, we adopted a
256	forward stepwise approach based on the Akaike information criterion (AIC) (Maydeu-
257	Olivares & García-Forero, 2010). Table 2 presents the fitted model (SDs from 8 out of
258	27 studies were estimated with this approach).

- 259
- 260

Table 2. Multiple linear regression model for estimating SD

Independent Variables	Coefficients	Standard Errors	t	<i>p</i> -value
Intercept	- 0.068	0.029	-2.317	.03
Mean	0.898	0.038	23.615	< .001

261	If neither the mean value nor SD were unavailable, but the sample size,
262	median, range, and/or interquartile range were available, we estimated the sample
263	mean and SD following the method by Wan et al. (2014). Finally, if either the mean
264	or the SD can be obtained using the above-mentioned approaches, the study was
265	omitted from the analysis, which led to an exclusion of 1 out of 28 studies.
266	At the same time, 3 studies only reported the MSAQ difference before and
267	after trials. Assuming that the MSAQ is similar among the population, we adopted the
268	MSAQ value of 15.4 as the pre-trial MSAQ (Karjanto et al., 2018; Karjanto et al.,
269	2022) and estimated the post-trial MSAQ using the difference reported in the studies
270	(3 out of 27). Then, the meta-analysis was performed in R with the "meta" package.
271	3. Results
272	In this section, we first discussed the qualitative findings from the literature
272 273	In this section, we first discussed the qualitative findings from the literature review. Then we report the meta-analysis results.
272 273 274	In this section, we first discussed the qualitative findings from the literature review. Then we report the meta-analysis results. 3.1. Influential factors
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282 condition that participants' eyes were closed or masked, so that they could not see283 anything).

Non-driving-related task (NDRT) availability: whether participants were
allowed/required to engage in NDRTs or not. Typical NDRTs include watching
videos and reading books.

- Artificial motion cues: cues provided through in-vehicle auditory, tactile, or visual interfaces regarding the current (i.e., present motion cues) or future motion states (i.e., anticipatory motion cues) of the ego-vehicle. Typical devices that were used to provide artificial motion cues include bring-in devices (e.g., wristband) and in-vehicle devices (LED mounted in the cabin).

292 - Head dynamic movement: the motion of occupants' heads in response to

293 vehicle dynamics movements (e.g., turning or accelerating), such as head tilting.

- Vehicle dynamics: including the factors related to the motion of the vehicles,

such as oscillation, acceleration, MSDV, and driving style of the driver.

- Internal layout: the internal layout of the vehicle cabin, for example, the length

of the cabin, angle of seats, position of in-vehicle displays, and form of windows (e.g.,

298 curvature and deformation of windows).

- Individual difference: factors related to the participants, for example, the

demographic information (e.g., age and gender), susceptibility to motion sickness, andsleep deprivation.

Others: other potential inducers that can be related to motion sickness but do
not belong to any of the above categories, such as field of view (FOV), predictability

304 of future motion (e.g., predictable motion vs. unpredictable motion), and odor in305 vehicles.

306 A Sankey diagram is further presented to visualize all inducers investigated in 307 the identified literature (see Figure 3), including what has been studied and how much 308 attention the researchers have paid to the inducers. In the diagram, the width of the 309 flow represents the number of literature for each corresponding inducer; the wider the 310 flow, the more attention it has gained from the researchers. From the diagram, it can 311 be observed that the artificial motion cues, vehicle dynamics, and eye views attracted the most attention from previous research. In addition, most of the motion sickness 312 313 studies were conducted in real cars (e.g., sedans or SUVs), followed by driving 314 simulators. Other studies were conducted using VR headset alone (sitting on a 315 rotating chair), the combination of VR with either car or driving simulators (e.g., a 316 VR-generated virtual environment that is inconsistent with the dynamics of a real 317 car), buses, oscillators, simulators on sled, and monitors alone (e.g., reproducing the 318 curvature and deformation of windows using monitors).



319

320 Figure 3. Sankey diagram of summarized influential inducers and experimental

environment (definitions of the abbreviations and terms can be found in section 3.1)

- 322 3.1.1. Eye View
- Nine studies have been identified that investigated the influence of eye view
 on motion sickness, in which the states of external view, internal view, and
 blindfolded view were manipulated (see Table 3). The results consistently show that

326	the "internal view" would lead to more severe motion sickness than the "external
327	view". However, the comparisons between "blindfolded view" and "external view"
328	generated inconsistent results in different studies. For example, in a 6-DoF simulator,
329	Li et al. (2022) compared the motion sickness of blindfolded occupants and occupants
330	with an external view (normal view) when the vehicle was controlled by driving
331	automation. The results showed that occupants with an external view experienced
332	more severe motion sickness compared to those who were blindfolded. However, in a
333	vehicle tested on the road, another study conducted by Wada and Yoshida (2016)
334	obtained contradictory results, in which the occupants with an external view
335	experienced significantly lower motion sickness than those with a blindfolded view.
336	The comparisons between "blindfolded view" and "internal view" also yielded
337	inconsistent results. For example, in Butler & Griffin (2009), two factors were
338	manipulated, i.e., the difference in phase between two kinds of vehicle oscillation
339	(fore-aft & pitch) and the type of eye view (internal vs. blindfolded). Results show
340	that in the in-phase condition (the pitch displacement was in the same phase as the
341	fore-and-aft displacement), the internal view led to more severe motion sickness than
342	the blindfolded view; while in the out-of-phase condition (the pitch displacement was
343	180° out of phase with the fore-and-aft displacement), blindfolded view led to more
344	severe motion sickness than internal view. These results indicate that the inducing
345	effect of eye view may vary when the vehicle dynamics are different. It may not be
346	enough to draw a unitary conclusion regarding the effects of eye view on motion

- 347 sickness induction. Future research is needed to further quantify the effects of
- 348 different inducers as well as their combinations on motion sickness in vehicles.
- 349
- 350

Table 3. Experiment results for eye view

Reference	Variable	Experimental environment	Motion sickness severity		
Bohrmann et al. (2022)	Internal vs. External view	Instrumented car	Internal > External		
Li et al. (2022)	Blindfolded vs. External view	6-DoF Simulator	External > Blindfolded		
Brietzke et al. (2021a)	Internal vs. External view	Instrumented car	Internal > External		
Irmak et al. (2021)	Internal vs. External view	Instrumented car	Internal > External		
Wada and Yoshida (2016)	Blindfolded vs. External view	Instrumented car	Blindfolded > External		
Butler and Griffin (2009)	Blindfolded vs. Internal vs. External view	Oscillator (fore-aft, pitch)	- In-phase: Internal > Blindfolded > External - Out-of-phase: Blindfolded > Internal > External		
Kato and Kitazaki (2006b)	Blindfolded vs. External view	Instrumented car	Blindfolded > External		
Probst et al. (1982)	Blindfolded vs. Internal vs. External view	Instrumented car	Internal > Blindfolded > External		
Cho and Kim (2022)	Internal vs. External view	VR + Instrumented car	Internal > External		

351 Note: In this table and the following tables, the symbol ">" means that the motion sickness severity

before the symbol was higher than that after the symbol.

353

354 3.1.2. NDRT availability

355 In-vehicle tasks that are non-related to driving would be more and more

- 356 prevalent with the development and popularity of driving automation. We identified
- 357 four studies that investigated the influence of NDRTs on motion sickness (see Table
- 4). All these studies indicate that engaging in NDRTs can increase the likelihood of
- 359 experiencing motion sickness. Further, occupants were found to be more likely to

360 experience motion sickness when reading books compared to when watching videos

- 361 (Isu et al., 2014).
- 362
- 363

Table 4. Experiment results for NDRT availability

ckness severity
ng > Video
No task
ng > Movie
No task
hing > No task
ng > No task
o task
r ::]]

364

365 3.1.3. Artificial motion cues

366	The influence of providing artificial motion cues has been studied in 23
367	studies (including a study that investigated both types of cues), of which 14 studies
368	investigated the effects of providing present motion cues to alleviate motion sickness
369	in vehicles, while 11 studies focused on providing anticipatory motion cues (see Table
370	5). It should be noted that in Mu et al. (2020), the navigation information was
371	available to drivers, which can inform both present and anticipatory motion
372	information. According to sensory conflict theory, motion sickness happens when the
373	visually perceived motion is inconsistent with the actual motion sensed by vestibular
374	(Saruchi et al., 2021). Thus, providing artificial motion cues to occupants is believed
375	to reduce this conflict and thus alleviate motion sickness. All of the research we
376	identified provided artificial motion cues to passengers, of which, the motion cue of
377	vehicle presented on HMI has been most commonly explored (13 out of 23). The

378	results from these studies, however, were not consistent. Specifically, 7 out of 14
379	studies that provided present motion cues and 2 out of 11 studies that provided
380	anticipatory cues found that introducing artificial motion cues would not alleviate
381	motion sickness among occupants. The effectiveness of providing artificial motion
382	cues in alleviating motion sickness will be discussed in the following meta-analysis.
383	
384	Table 5. Experiment results for artificial motion cues

Reference	Variable	Experimental environment	Motion sickness severity (w/ vs. w/o)		
Bohrmann et al. (2022)	Present motion cues (LED)	Instrumented	No effect		
de Winkel et al. (2021)	Present motion cues (LED)	VR + hexapod motion simulator	No effect		
Mu et al. (2020)	Present motion cues (HMI)	Instrumented car	Decrease		
	Anticipatory motion cues (HMI)	Instrumented car	Decrease		
Meschtscherjakov et al. (2019)	Present motion cues (HMI)	Instrumented car	Decrease		
Ihemedu-Steinke et al. (2018)	Present motion cues (HMI)	VR + 2-DoF simulator	Decrease		
Hanau and Popescu (2017)	Present motion cues (HMI)	Bus	No effect		
Miksch et al. (2016)	Present motion cues (HMI)	Instrumented car	Decrease		
Morimoto et al. (2008b)	Present motion cues (HMI)	Instrumented car	Decrease		
Kato and Kitazaki (2008)	Present motion cues (HMI)	Instrumented car	Decrease		
Kato and Kitazaki (2006b)	Present motion cues (HMI)	Instrumented car	Decrease		
Brietzke et al. (2021b)	Present motion cues (HMI)	Instrumented car	No effect		
Cho and Kim (2022)	Present motion cues (LED)	VR + Instrumented car	No effect		
Li and Chen (2022)	Anticipatory motion cues (vibrator)	6-DoF Simulator	Decrease		
Yusof et al. (2020)	Anticipatory motion cues (vibrator)	Instrumented car	Decrease		
Hainich et al. (2021)	Anticipatory motion cues (HMI)	Instrumented car	Decrease		
de Winkel et al. (2021)	Anticipatory motion cues (LED)	VR + hexapod motion simulator	No effect		

Anticipatory motion cues (LED)

Karjanto et al. (2018)

Table 5. Experiment results for artificial motion cues

Experimental

Instrumented

car

Decrease

Motion sickness

Maculewicz and Larsson (2021)	Anticipatory motion cues (audio)	Instrumented car	Decrease
Suwa et al. (2022)	Present motion cues (HMI)	Fixed-base simulator (with vibration)	Decrease
Kuiper et al.(2020)	Anticipatory motion cues (audio)	Sled	No effect
Karjanto et al.(2017)	Anticipatory motion cues (LED)	Instrumented car	Decrease
McGill et al. (2017)	Present motion cues (HMI)	VR + instrumented car	No effect
Reuten et al.(2023)	Anticipatory motion cues (vibrator)	Sled	No effect
Lin et al. (2005)	Anticipatory motion cues (HMI)	Simulator (DoF unknown)	Decrease

385

386 3.1.4. Head Dynamic Movement

387 We identified five studies that investigated the influence of occupants' head 388 dynamic movement on motion sickness. Three of them focused on the alignment of 389 the head to the tilting inertial resultant (gravity and imposed horizontal acceleration, 390 or for short: gravito-inertial force (GIF)); the other two focused on the 391 centrifugal/centripetal head tilting in cornering. 392 Alignment with GIF: The effects of alignment with GIF on motion sickness are inconclusive. Golding et al. (2003) investigated the influence of active/passive 393 394 mis-/alignment of head to GIF on motion sickness when the vehicle had fore-and-aft 395 acceleration. In the active mis-/alignment situation the head tilt was actively 396 controlled by participants; while in the passive mis-/alignment situation the head tilt 397 was controlled by an actuated seat. The results showed that active head alignment 398 could postpone the occurrence of moderate nausea compared to active head 399 misalignment. At the same time, in the passive alignment situation, time before

400 reporting sickness was shorter in the aligned condition compared to that in the 401 misaligned condition. Similarly, Sugiura et al. (2019) tested the concept of the lean 402 function of the chassis in order to mitigate motion sickness. With such a function, the 403 occupant's head can be aligned towards the GIF direction and it was found that the 404 motion sickness was significantly alleviated, with a lower percentage of people 405 experiencing severe motion sickness. However, contradictory results have also been 406 observed. In Brietzke et al. (2021b), an actuated seat was designed to compensate for the vehicle's fore-and-aft acceleration so that the spine, thorax, and rotation movement 407 408 of the occupants' heads can be reduced. The results showed that such an actuated seat 409 was not able to alleviate the motion sickness of occupants.

410 Tilt in cornering: Changing the head tilt in cornering can affect occupants' 411 susceptibility to motion sickness. Wada et al. (2012) found that the active head-tilt 412 (specifically, adopting a centripetal head-tilt in which participants tilted their heads 413 counter to the direction of centrifugal acceleration) could both postpone the 414 occurrence of motion-sickness-related symptoms and reduce the total symptom 415 scores. Similarly, Wada and Yoshida (2016) found that the centripetal head tilt could 416 reduce the sickness rating significantly.

417 3.1.5. Vehicle Dynamics

418 **Oscillation:** Motion sickness in vehicles was found to be related to both the 419 frequency and the amplitude of the oscillation of the vehicle. In a 6-DoF simulator,

420 Kuiper et al. (2019) found that the participants exposed to the lateral sinus oscillation

421 at 0.2 Hz experienced a higher severity of motion sickness compared to that at 0.35

422	Hz. However, this difference did not reach a significant level ($p > .05$). Two other
423	studies found that the motion sickness varied with the horizontal (fore-aft) sinus
424	motion frequency of the vehicle, i.e., from 0.1 to 0.4 Hz (Golding et al., 2001) and
425	from 0.35 to 1 Hz (Golding et al., 1997) and the maximum severity of motion
426	sickness was at 0.2 Hz and 0.35 Hz, respectively. DiZio et al. (2018) have compared
427	the influence of a commercial active suspension system (unmitigated ride) and an
428	active cancellation system (mitigated ride) on motion sickness among occupants. The
429	results showed that when the occupants were doing a reading task, the motion
430	sickness could be induced in the frequency range between 0.8 Hz to 8 Hz. The authors
431	attributed the increased motion sickness within this frequency range to the high
432	possibility of retinal slip as a result of the oscillation, because the vestibular-ocular
433	reflex (VOR) that stabilizes the eye in space also has a high gain between 0.8 Hz to 8
434	Hz. Regarding the influence of the amplitude of the oscillation, Irmak et al. (2022)
435	compared the influence of the amplitude of fore-aft acceleration $(1, 1.5, 2, 2.5 \text{ m/s}^2)$
436	on the severity of motion sickness. Results show that the severity of motion sickness
437	(scaled in MISC) increased linearly with the amplitude of oscillation.
438	The absolute value of acceleration: The absolute value of acceleration may

440 results have been achieved. For example, in an 8-DoF simulator study, Jurisch et al.

be associated with the severity of motion sickness in vehicles, though no conclusive

441 (2020) investigated the effects of using an active suspension system on the mitigation

442 of motion sickness, in which the active suspension can reduce the high lateral

439

443 acceleration of vehicles experienced by passengers. However, no significant benefits

444	have been observed in this study. While in another study, Wang et al. (2021) analyzed
445	the relationship between the motion sickness and bus dynamics. It was found that the
446	time before experiencing motion sickness could be predicted (79.8%) by the lateral
447	acceleration, roll, and pitch angular velocity of the bus. Mixed results were observed
448	by Jones et al. (2019), in which, the authors focused on the association between
449	longitudinal acceleration and motion sickness severity. It was found that when
450	NDRTs were unavailable, no difference in motion sickness between low and
451	moderate acceleration was observed; while when occupants were provided with
452	NDRTs (i.e., visual searching and typing tasks), moderate acceleration led to a higher
453	severity of motion sickness compared to that of low acceleration. The combination of
454	accelerations from different directions was investigated as well. For example, in a
455	simulator study, Wijlens et al. (2022) investigated whether the motion sickness of
456	passengers in an autonomous vehicle was associated with the combination of
457	longitudinal and lateral acceleration. In Condition 1, the vehicle had larger
458	longitudinal but smaller lateral acceleration; in Condition 2, the vehicle had smaller
459	longitudinal but larger lateral acceleration. It was found that the motion sickness in
460	Condition 1 was more severe than that in Condition 2 though the difference did not
461	reach a significant level ($p > .05$).
462	MSDV: In addition to the absolute value of the lateral acceleration, the
463	MSDV (Wiederkehr & Altpeter, 2013) has also been found to be associated with the
464	severity of motion sickness in passengers and has been commonly adopted in previous

465 research. The MSDV is a mathematically calculated value that can be used to evaluate

466	how vehicle dynamics may lead to motion sickness and can be further categorized as
467	MSDVx and MSDVy, representing the accumulated acceleration in the longitudinal
468	and lateral directions. However, the association between the MSDV and severity of
469	motion sickness ratings is not conclusive either. For example, Turner & Griffin
470	(1999b) found that MSDVx ($R^2 = 0.77$) and MSDVy ($R^2 = 0.79$) were correlated to
471	the motion sickness of passengers in a bus that was measured by a subjective
472	questionnaire (i.e., a four-point subjective rating of illness and a question about the
473	symptoms of motion sickness). In another study, Kato and Kitazaki (2006a) found
474	that the MSDVs of head lateral motion were significantly correlated with motion
475	sickness ratings in cars. However, in another study focusing on motion sickness in a
476	stop-and-go-scenario, the R^2 of the fitted model was only 2.7% when the eye view
477	condition, MSDV level, and susceptibility to motion sickness were used to predict the
478	motion sickness ratings (Brietzke et al., 2021a). Further, when motion sickness
479	adaption appeared, the MSDV was not able to predict the motion sickness ratings
480	(Yunus et al., 2022).

Driving style: Strictly speaking, driving style cannot be treated as an independent inducer of motion sickness, as the driving style is associated with and can even be defined by a number of factors/inducers described above. For example, an aggressive driving style is commonly associated with large lateral and longitudinal acceleration (Vaiana et al., 2014). However, we still list driving style as an inducer here considering that there are some other characteristics of driving style that are not captured by the above-mentioned factors/inducers, such as the headway distance and 488 the vehicle speed (Khan et al., 2021). Driving style has been found to be associated 489 with drivers' severity of motion sickness in vehicles. For example, Karjanto et al. 490 (2022) found that when NDRTs were allowed for passengers, an aggressive driving 491 style led to more severe motion sickness than that of a conservative driving style 492 among passengers, potentially due to the large absolute acceleration in longitudinal, 493 lateral and vertical directions associated with the aggressive driving style. 494 Phase difference: The phase difference was defined as the difference between the fore-aft oscillation and the pitch oscillation. Butler and Griffin (2009) found that 495 the phase difference had no significant effect on motion sickness. 496 497 3.1.6. Internal Layout 498 Seat layout: Salter et al. (2019) compared the influence of cabin length (short cabin vs. long cabin), slight seat rotation (0° vs. 10° inboard rotation), and seat 499 500 orientation (forward vs. rearward facing) on motion sickness. It was found that the 501 cabin length and slight seat rotation were not associated with the severity of motion 502 sickness; while the rearward seating was associated with a higher likelihood of motion 503 sickness compared to that of forward seating. 504 **Display position:** The position of the in-vehicle display can affect occupants' 505 head position and their eye view. Previous research found that a higher display 506 position (at the height of the windshield) was more likely to induce motion sickness

- 507 compared to when the display position was lower (at the height of the glove
- 508 compartment) (Kuiper et al., 2018). It is explained that, compared to a lower display

509 position, a higher display position led to better visibility of the road environment,

510 which allowed better perception of the motion of the ego-vehicle.

511 Windows shape: Fujita and Nakanishi (2017) investigated whether and how 512 the warp and deformation of the window can lead to motion sickness in vehicles. 513 Results showed that the vertical deformation of windows was more likely to induce 514 motion sickness than that of horizontal deformation. In addition, if a window had no 515 deformation, then blending the glass of the windows would decrease motion sickness. 516 Coordinate system of HMD: HMD (Head-mounted display) is a new way of 517 providing information in vehicles. In a simulator study, Sato et al. (2022) investigated 518 the influence of the HMD coordinate system on motion sickness in vehicles when 2D 519 content was displayed in HMD. Two types of coordinates were used, i.e., the head-520 fixed coordinate (i.e., the content in HMD will move with the motion of occupants' 521 head) and earth-fixed coordinate (i.e., the content in HMD is fixed relative to the 522 ground). It was found that the severity of motion sickness was significantly lower 523 when an earth-fixed HMD was used, as compared to when a head-fixed HMD was 524 used.

525 3.1.7. Individual Difference

It has been widely acknowledged that individual differences exist in terms of susceptibility to motion sickness (Turner & Griffin, 1999a). Questionnaires have been designed to measure the individual differences in susceptibility to motion sickness, for example, the MSSQ (Motion Sickness Susceptibility Questionnaire) or MSSQs (Motion Sickness Susceptibility Questionnaire—short). As can be expected, a higher

531	susceptibility was found to be associated with a higher likelihood of experiencing
532	motion sickness in most of the identified studies (Jones et al., 2019; Brietzke et al.,
533	2021a; Bohrmann et al., 2022; Meschtscherjakov et al., 2019). However, an
534	insignificant correlation between motion sickness suscepetibility and motion sickness
535	severity has also been reported in one study that investigated the influence of
536	horizontal oscillation on motion sickness using a driving simulator (Kuiper et al.,
537	2019). In addition, the susceptibility to motion sickness has also been found to be
538	associated with occupants' age. For example, Jones et al. (2019) found that occupants
539	aged below 60 were more likely to experience more severe motion sickness compared
540	to those who were above 60. Finally, living habits can also influence the susceptibility
541	to motion sickness. Kaplan et al (2017) found that when exposed to identical linear
542	oscillation, those who had inadequate sleep reported higher levels of motion sickness
543	compared to those with sufficient sleep.
544	3.1.8. Other Factors
545	FOV: Pöhlmann et al. (2022) compared the influence of different FOV (full

546 FOV vs. partial FOV) on motion sickness in VR-based simulators but found no547 significant effect.

548 Scent: Schartmüller and Riener (2020) investigated the influence of in-vehicle
549 odor (ginger and lavender) on motion sickness but, again, no significant effect has
550 been observed.

551 Predictability: The motion sickness under automated driving mode and552 manual driving mode has been compared in two independent driving simulation

553 studies (Li et al., 2022; Zhao et al., 2019). Both studies found that in manual driving 554 mode, active drivers were less likely to get motion sickness, potentially due to the higher predictability of vehicle motion under manual driving mode. Another research 555 556 compared motion sickness under fore-and-aft motion with different levels of predictability (directionally unpredictable vs. temporally unpredictable vs. fully 557 558 predictable). The results showed that, in the condition of fully predictable motion, the 559 motion sickness severity was significantly lower than that under two other conditions 560 (Kuiper et al., 2020).

Seated position: A comparative study investigated the occurrence of motion sickness resulting from frequent horizontal linear acceleration in an ambulance car, considering three distinct seated positions: sitting upright facing forward, lying supine with the head pointing forward, and lying supine with the head pointing backward. The findings revealed a notably greater prevalence of motion sickness when seated upright compared to the other two postures. However, no significant difference in motion sickness was observed between the two reclined postures (Vogel et al., 1982).

568 3.2. Results of Meta-Analysis

As no conclusive results have been obtained in previous studies, a metaanalysis was conducted to examine the effects of providing motion cues (present motion cues and anticipatory motion cues based on artificial information) on alleviating motion sickness. It should be noted that the presence of the motion cues can be manipulated by more than controlling the availability of artificial motion cues (e.g., by providing navigation information in human-machine interfaces); but can also 575 be manipulated by controlling the eye view and NDRT availability. Specifically, the 576 internal view can block the present motion cue; while with the external view, participants can perceive the present motion cue. Similarly, engaging with NDRTs 577 578 (e.g., reading a book or watching a video) can affect the perception of the present 579 motion cues as well. Thus, in the meta-analysis, the eye view and NDRT availability 580 were considered as a manipulation of the natural present motion cues (e.g., based on 581 which the occupants can judge the present relative movement between the ego-vehicle 582 and the surrounding environment without using artificial cues). Thus, in the meta-583 analysis, we further categorized the present motion cues into the artificial present 584 motion cues and the natural present motion cues. 585 3.2.1. Present Motion Cues 586 In total, 20 studies encompassing 25 relevant experiments were identified, all

of which targeted towards the effect of present motion cues on motion sickness (Table
6). Overall, the effects of natural present motion cues on alleviating motion sickness
have been observed in 14 experiments; while the effects of providing artificial present
motion cues have been observed in the rest 11 experiments. In all experiments, the
artificial present motion cues were conveyed through visual displays, including LED

592 stripes and bring-in devices (e.g., phones and tablets).

For the identified studies, Egger's test was used to examine the publication bias among the identified studies, and no publication bias was observed (p = 0.13), indicating that no identified study was systematically unrepresentative of the population of completed studies and disproportionately favored certain outcomes

- 597 (Viechtbauer, 2007). Further, the effects of experiments were well-distributed on both
 598 sides of the overall mean effect (Figure 5) and the sensitivity test showed that the
- 599 overall effect was stable, indicating that the influence of each single paper on the
- 600 overall results was acceptable (Figure 6).

Experimental				Control	Standardised Mean					
Study	Total	Mean	SD	Total	Mean	SD	Difference	SMD	95%-CI	Weight
Group = Artificial present motion cues (visual)										
de Winkel et al.(2021)	19	5.89	3.1800	19	5.53	2.8100		0.12	[-0.52; 0.76]	4.5%
Mu et al.(2020)	3	4.33	3.5000	3	5.00	1.7300		-0.19	[-1.80; 1.42]	1.1%
Miksch et al.(2016)	12	1.27	0.5400	12	1.62	0.8400		-0.48	[-1.29; 0.34]	3.4%
Bohrmann et al.(2022)	23	27.00	16.1875	23	28.00	13.8700		-0.07	[-0.64; 0.51]	5.0%
Brietzke et al.(2021b)	20	2.30	2.2300	20	2.35	2.3500		-0.02	[-0.64; 0.60]	4.7%
Cho and Kim(2022)	15	190.70	67.2300	8	256.62	264.7400		-0.39	[-1.26; 0.48]	3.1%
Kato and Kitazaki(2008)	38	1.54	0.7000	19	1.99	1.1100		-0.52	[-1.08; 0.04]	5.2%
Meschtscherjakov et al. (2019)	10	18.01	9.3900	10	27.46	17.8800		-0.63	[-1.54; 0.27]	2.9%
Hanau and Popescu (2017)	19	0.34	0.1860	7	0.34	0.1800		-0.01	[-0.88; 0.85]	3.1%
McGill et al. (2017)	36	29.50	27.9800	18	31.20	28.9000		-0.06	[-0.63; 0.51]	5.1%
Random effects model	195			139			•	-0.19	[-0.42; 0.03]	38.0%
Heterogeneity: $I^2 = 0\%$, $\tau^2 = 0$, p	= 0.86									
Group = Natural present mo	tion c	les								
Brietzke et al.(2021a)	319	1.10	1.2800	318	2.84	2.5400		-0.86	[-1.03; -0.70]	9.3%
Irmak et al.(2021)	18	3.20	2.8000	18	5.45	2.6000		-0.81	[-1.50; -0.13]	4.2%
Bohrmann et al.(2022)	23	24.00	11.5625	23	31.00	16.1875		-0.49	[-1.08; 0.10]	4.9%
Probst et al.(1982)	14	0.79	1.1200	14	5.50	2.7200		-2.20	[-3.16; -1.23]	2.6%
Cho and Kim(2022)	7	256.62	264.7400	15	420.14	374.2200		-0.46	[-1.37; 0.45]	2.9%
lsu et al.(2014)	10	1.70	1.3400	40	5.00	2.7000		-1.30	[-2.04; -0.56]	3.8%
Suwa et al.(2022)	20	2.18	2.2300	20	3.12	2.2300	- <u>i=</u> +	-0.41	[-1.04; 0.21]	4.6%
Butler and Griffin(2009)	20	1.17	0.6400	20	2.15	1.5200		-0.82	[-1.47; -0.18]	4.4%
Butler and Griffin(2009)	20	1.01	0.5000	20	2.08	1.4600		-0.96	[-1.62; -0.30]	4.4%
Morimoto et al.(2008a)	31	2.15	1.2500	62	5.12	3.9200		-0.90	[-1.35; -0.44]	6.2%
Morimoto et al.(2008b)	14	4.38	3.2600	42	8.10	6.6000		-0.61	[-1.23; 0.00]	4.7%
Kato and Kitazaki(2005)	20	0.43	-0.0200	60	1.27	0.7300				0.0%
Jones et al.(2019)	26	1.84	0.9700	26	4.85	3.6800		-1.10	[-1.69; -0.52]	4.9%
Jones et al.(2019)	26	2.23	1.3200	26	3.84	2.7700		-0.73	[-1.29; -0.17]	5.1%
Random effects model	568			704			*	-0.85	[-0.98; -0.73]	62.0%
Heterogeneity: $I^2 = 18\%$, $\tau^2 = < 0.0001$, $p = 0.27$										
Random effects model	763			843				-0.61	[-0.79; -0.43]	100.0%
Heterogeneity: $I^{-} = 51\%$, $\tau^{-} = 0.0873$, $p < 0.01$										
Lest for subgroup differences: χ	Test for subgroup differences: $\chi_1 = 26.01$, at = 1 ($p < 0.01$) -3 -2 -1 0 1 2 3									



601

Figure 4. Forest plot for subgroup analysis of present motion cues



Funnel Plot (present motion cues) of pseudo 95% confindence limits



Oda a da a	Standard	ised Mean	0.40	05% 01	Duralius	T0	T	10
Study	Diffe	rence	SIVID	95%-01	P-value	Tauz	Tau	12
Omitting Brietzke et al.(2021a)		1	-0.58	[-0.78; -0.39]	< 0.01	0.0922	0.3036	46%
Omitting Irmak et al. (2021)			-0.60	[-0.79; -0.41]	< 0.01	0.0954	0.3088	53%
Omitting de Winkel et al. (2021)			-0.65	[-0.82; -0.47]	< 0.01	0.0660	0.2569	46%
Omitting Mu et al.(2020)			-0.61	[-0.80; -0.43]	< 0.01	0.0892	0.2986	53%
Omitting Miksch et al. (2016)			-0.61	[-0.80; -0.42]	< 0.01	0.0945	0.3074	53%
Omitting Bohrmann et al.(2022)	— <u>•</u>		-0.64	[-0.82; -0.46]	< 0.01	0.0764	0.2765	48%
Omitting Bohrmann et al. (2022)	_		-0.62	[-0.81; -0.42]	< 0.01	0.0976	0.3124	53%
Omitting Probst et al.(1982)			-0.57	[-0.74; -0.41]	< 0.01	0.0586	0.2421	42%
Omitting Brietzke et al. (2021b)			-0.64	[-0.82; -0.46]	< 0.01	0.0758	0.2753	48%
Omitting Cho and Kim(2022)			-0.61	[-0.80; -0.43]	< 0.01	0.0934	0.3056	53%
Omitting Cho and Kim(2022)			-0.62	[-0.81; -0.43]	< 0.01	0.0931	0.3051	53%
Omitting Isu et al.(2014)			-0.58	[-0.77; -0.40]	< 0.01	0.0793	0.2817	51%
Omitting Suwa et al. (2022)			-0.62	[-0.81; -0.43]	< 0.01	0.0955	0.3090	53%
Omitting Butler and Griffin(2009)			-0.60	[-0.79; -0.41]	< 0.01	0.0955	0.3090	53%
Omitting Butler and Griffin(2009)			-0.59	[-0.78; -0.40]	< 0.01	0.0915	0.3025	53%
Omitting Morimoto et al.(2008a)			-0.59	[-0.78; -0.40]	< 0.01	0.0932	0.3053	53%
Omitting Morimoto et al. (2008b)			-0.61	[-0.80; -0.42]	< 0.01	0.0983	0.3135	54%
Omitting Kato and Kitazaki(2008)			-0.61	[-0.81; -0.42]	< 0.01	0.0986	0.3140	53%
Omitting Kato and Kitazaki(2005)			-0.61	[-0.79; -0.43]	< 0.01	0.0873	0.2954	51%
Omitting Jones et al.(2019)			-0.58	[-0.77; -0.40]	< 0.01	0.0833	0.2887	52%
Omitting Jones et al. (2019)			-0.60	[-0.80; -0.41]	< 0.01	0.0984	0.3136	54%
Omitting Meschtscherjakov et al. (2019)			-0.61	[-0.80; -0.42]	< 0.01	0.0942	0.3069	54%
Omitting Hanau and Popescu (2017)			-0.63	[-0.81; -0.44]	< 0.01	0.0847	0.2911	51%
Omitting McGill et al. (2017)			-0.64	[-0.82; -0.46]	< 0.01	0.0751	0.2740	48%
Random effects model		<u> </u>	-0.61	[-0.79; -0.43]	< 0.01	0.0873	0.2954	51%
	-0.5	0 0.5						

Figure 6. Influence analysis of each study for present motion cues

Litonotuno	Bas	eline Group		Treat	ment group	1	Control variable	Catagory of inducan	Exposure	Experimental	
	n	Mean	SD	n	Mean	SD	(Baseline vs. Treatment)	Category of inducers	time (min)	Environment	
Brietzke et al. (2021a)	318	2.8	2.5	319	1.1	1.3	Internal view vs. External view	Natural present motion cues	11	Vehicle	
Irmak et al. (2021)	18	5.5	2.6	18	3.2	2.8	Internal view vs. External view	Natural present motion cues	30	Vehicle	
de Winkel et al. (2021)	19	5.7	2.9	19	5.9	3.3	Present motion cues (w/ vs. w/o)	Artificial present motion cues	10	Simulator	
Mu et al. (2020)	3	5	1.7	3	4.3	3.5	Present motion cues (w/ vs. w/o)	Artificial present motion cues	10	Vehicle	
Miksch et al. (2016)	12	1.6	0.8	12	1.3	0.5	Present motion cues (w/ vs. w/o)	Artificial present motion cues	10	Vehicle	
Bohrmann et al.	23	28	13.8	23	27	16.2	Present motion cues (w/ vs. w/o)	Artificial present motion cues	20	Vahiala	
(2022)	23	31	16.2	23	24	11.6	Internal view vs. External view	nal view Natural present motion		Vehicle	
Probst et al. (1982)	14	5.5	2.7	14	0.8	1.1	Internal view vs. External view	Natural present motion cues	6.33	Vehicle	
Brietzke et al. (2021b)	20	2.4	2.4	20	2.3	2.2	Present motion cues (w/ vs. w/o)	Artificial present motion cues	11	Vehicle	
	15	420.1	374.2	7	256.6	264.7	VR: Internal view vs. External view	Natural present motion cues	5	X7.1.1	
Cho and Kim (2022) —	8	256.6	264.7	15	190.7	67.2	VR: Present motion cues (w/ vs. w/o)	Artificial present motion cues	5	Vehicle	
	20	5.3	2.2	10	1.7	1.3	NDRT vs. No NDRT	Natural present motion cues	15	X7.1.1	
Isu et al. (2014) —	20	4.7	3.1	10	1.7	1.3	NDRT vs. No NDRT	Natural present motion cues	15	Venicle	
Suwa et al. (2022)	20	3.1	2.2	20	2.2	2.2	Present motion cues (w/ vs. w/o)	Artificial present motion cues	20	Simulator	
Butler and Griffin	20	2.2	1.5*	20	1.2	0.6*	Internal view vs. External view	Natural present motion cues	30	0. 14	
(2009)	20	2.1	1.5*	20	1.0	0.5*	Internal view vs. External view	Natural present motion cues	30	Simulator	
Morimoto et al. (2008a)	62	5.1	3.9*	31	2.2	1.3*	NDRT vs. No NDRT	Natural present motion cues	15	Vehicle	
Morimoto et al. (2008b)	42	8.1	6.6*	14	4.4	3.3*	NDRT vs. No NDRT	Natural present motion cues	21	Vehicle	
Kato and Kitazaki (2008)	19	2.0	1.1*	38	1.5	0.7*	Present motion cues (w/ vs. w/o)	Artificial present motion cues	30	Vehicle	

Table 6. Studies included for the meta-analysis of present motion cues

Kato and Kitazaki (2005)	60	1.3	0.7*	20	0.4	0.0*	NDRT vs. No NDRT	Natural present motion cues	30	Vehicle
$I_{2} = \frac{1}{2} \left(\frac{1}{2} \right) \left(\frac{1}{2} \right)$	26	4.85	3.7*	26	1.8	1.0*	NDRT vs. No NDRT	Natural present motion cues	20	Vehicle
Jones et al. (2019) —	26 3.8 2.8* 26 2.2 1.3* NDRT vs. No NDRT		NDRT vs. No NDRT	Natural present motion cues	20	Vehicle				
Meschtscherjakov et al. (2019)	10	27.5	17.9*	10	18.0	9.4*	Present motion cues (w/ vs. w/o)	Artificial present motion cues	20	Vehicle
Hanau and Popescu (2017)	7	0.3	0.2	19	0.3	0.2	Present motion cues (w/ vs. w/o)	Artificial present motion cues	20	Vehicle
McGill et al. (2017)	18	31.2	28.9	36	29.5	28.0	VR: Present motion cues (w/ vs. w/o)	Artificial present motion cues	10	Simulator

Note: In this table and the following tables, the SD stands for standard deviation and n stands for sample size. The SD with * means that the value is estimated through the

multiple linear regression model presented in Table 2.

553	Considering the heterogeneity between the studies ($I^2 = 51\%$, $p < .01$), a random-
554	effects model was adopted for the meta-analysis (see Figure 4). In general, perceiving present
555	motion cues can decrease motion sickness, $SMD = -0.61$, with a 95% confidence interval
556	(95%CI) between - 0.79 to - 0.43. Further, to explain the heterogeneous results between
557	studies, meta-regression was conducted to analyze the influence of different factors on
558	motion sickness, including types of cues (natural present motion cues vs. artificial present
559	motion cues), exposure time, and experimental environment (vehicle vs. simulator). For the
560	selection of the models, we adopted a forward stepwise model selection approach based on
561	the AIC. The category of inducers, experimental environment, and exposure time were
562	always kept in the model as they are the variables of interest for this study; while their two-
563	way interactions were added into the model step by step. Table 7 presents the final model. It
564	was found that only the type of cues had a significant effect on the motion sickness severity.
565	

566

Table 7. The results of meta-regression for present motion cues

Independent Variables	Coefficients	Standard Errors	t	<i>p</i> -value	95% CI
Types of cues:	-0.6168	0.128	-4.824	.0001	[-0.884, -0.349]
Natural present motion cues					
Experimental environment:	0.1986	0.143	1.394	.2	[-0.100, 0.500]
Simulator					
Exposure time	-0.0005	0.008	-0.063	.95	[-0.017, 0.016]
Intercept	-0.2542	0.168	-1.516	.14	[-0.605, 0.097]

567

A subgroup analysis for different types of motion cues was then conducted. The heterogeneity of each subgroup becomes lower (natural present motion cue: $I^2 = 18\%$, p = .3; Artificial present motion cues: $I^2 = 0.0\%$, p = .9) than that of overall heterogeneity. The results for each subgroup showed that only the natural present motion cues (SMD = - 0.85, 95%CI: [- 0.98, - 0.73]) significantly reduced the severity of motion sickness; while the artificial present motion cues had no significant effects (SMD = - 0.19, 95%CI: [-0.42, 0.03]). 574 The statistical heterogeneity of both subgroups was insignificant, indicating that the variation 575 of outcome within the group was low (Higgins & Green, 2008).

- 576
- 577 3.2.2. Anticipatory Motion Cues

578 A meta-analysis was also conducted for the effect of anticipatory motion cues (Table 9). No heterogeneity was observed ($I^2 = 0\%$, p = 0.6), thus a fixed effect model (also referred 579 to as "common effect model" in R) was used for meta-analysis (Figure 7). It was found that 580 581 the motion sickness severity can be mitigated by providing anticipatory motion cues (SMD = 582 - 0.35, 95%CI: [-0.56 to -0.14]). An Egger's test was used for the test of publication bias and 583 a sensitivity test was used to analyze the influence of a single experiment on the overall result 584 (see Figure 8 and Figure 9). No publication bias was found (p = 0.9) and no single 585 experiment could change the results significantly.

586 Following the same approach described in section 3.2.1, a meta-regression was 587 constructed to examine the impact of the modality of the cues, exposure time, experimental 588 environment (vehicle vs. simulator), and their interactions on the motion sickness severity. In 589 order to meet the minimal study size criteria for both meta-regression and subgroup analysis 590 (each category should comprise a minimum of 4 studies, Fu et al., 2011), for the modality of the cues, tactile and auditory cues were aggregated as the non-visual cues, whereas other 591 592 visual information were grouped as the visual cues. None of the factors reached a significant 593 level of .05, as shown in Table 8.

Table 8. The results of meta-regression for anticipatory motion cues

Independent Variables	Coefficients	Standard Errors	t	<i>p</i> -value	95% CI
Modal: visual	0.2396	0.251	0.956	.4	[-0.373, -0.853]
Experimental environment: Simulator	0.2826	0.232	1.218	.4	[-0.285, 0.851]
Exposure time	-0.0053	0.018	-0.290	.8	[-0.050, 0.039]
Intercept	-0.5142	0.384	-1.341	.2	[-1.453, 0.424]

Table 9. Studies included for meta-analysis of anticipatory motion cues

Reference		Baselin	ie		Treatme	nt	Control Variable	Modal of Anticipatomy Cuos	Exposure time	Experimental
	n	mean	SD	n	mean	SD		Anticipatory Cues	(mm)	Environment
Maculewicz and Larsson (2021)	20	3.4	1.7	20	2	1.5	Anticipatory motion cues (w/ vs. w/o) (auditory)	Non-visual	30	Vehicle
de Winkel et al. (2021)	19	5.7	2.9	19	5.8	2.7	Anticipatory motion cues (w/ vs. w/o) (visual)	Visual	10	Simulator
Li and Chen (2022)	20	2.6	1.3	20	1.8	1.3	Anticipatory motion cues (w/ vs. w/o) (tactile)	Non-visual	7	Simulator
	8	23.4	15.8	20	13.4	19.0	Anticipatory motion cues (w/ vs. w/o) (visual)	Visual	15	Vehicle
Hainich et al. (2021)	8	5.6	3.1	8	7.7	7.2	Anticipatory motion cues (w/ vs. w/o) (visual)	Visual	15	Vehicle
Mu et al. (2020)	3	5	1.7	3	4.3	3.5	Anticipatory motion cues (w/ vs. w/o) (visual)	Visual	10	Vehicle
Karjanto et al.(2018)	20	28.3	16.9	20	20.9	5.1	Anticipatory motion cues (w/ vs. w/o) (visual)	Visual	8.5	Vehicle
Kuiper et al.(2020)	20	4.2	1.8	20	3.5	2.2	Anticipatory motion cues (w/ vs. w/o) (auditory)	Non-visual	15	Simulator
Yusof et al.(2020)	20	24.9	16.9	20	20.5	7.5	Anticipatory motion cues (w/ vs. w/o) (tactile)	Non-visual	10	Vehicle
Reuten et al.(2023)	24	3.0	2.0*	72	2.7	1.7*	Anticipatory motion cues (w/ vs. w/o) (tactile)	Non-visual	15	Simulator

We conducted further a subgroup analysis for different cues with different modalities (see Figure 7). No significant heterogeneity was observed for either the visual cues ($I^2 = 0\%$, p = 0.4) or the non-visual cues ($I^2 = 0\%$, p = 0.5). The synthesis effect size showed that only the non-visual anticipatory cues could reduce motion sickness (SMD = - 0.41, 95%CI: [-0.67 to -0.15]), while the effect of visual anticipatory cues was insignificant (SMD = - 0.24, 95%CI: [-0.61 to 0.13]).

		Expe	rimental			Control	Standardised Mean			
Study	Total	Mean	SD	Total I	Mean	SD	Difference	SMD	95%-CI	Weig
mode group = non-visual										
Maculewicz and Larsson (2021)	20	2.00	1.5000	20	3.40	1.7000		-0.86	[-1.51; -0.21]	10.8
Li and Chen(2022)	20	1.80	1.3400	20	2.60	1.3400		-0.59	I-1.22: 0.051	11.3
Kuiper et al. (2020)	20	3.45	2.1900	20	4.15	1.8200		-0.34	1-0.97: 0.281	11.7
Yusof et al. (2020)	20	20.45	7,4800	20 2	24.93	16,9000		-0.34	[-0.96: 0.29]	11.7
Reuten et al (2023)	72	2 69	1 7400	24	2 98	2 0000		-0.16	[-0.62 0.30]	21.3
Common effect model	152			104				-0.41	[-0.67: -0.15]	66.6
Heterogeneity: $I^2 = 0\%$, $\tau^2 = 0$, $p =$	= 0.50									
mode group = visual										
de Winkel et al. (2021)	19	5.58	2.5200	19	5.53	2.8100		0.02	[-0.62; 0.66]	11.2
Karjanto et al.(2018)	20	20.85	5.1286	20 2	28.27	16.9000		-0.58	[-1.22; 0.05]	11.3
Hainich et al.(2021)	8	13.37	16.0700	8 2	23.36	13.3000		-0.64	[-1.65; 0.37]	4.4
Hainich et al. (2021)	8	7.68	7.2300	8	5.59	3.0500		0.36	[-0.63; 1.35]	4.6
Mu et al.(2020)	3	4.33	3.5000	3	5.00	1.7300		-0.19	[-1.80; 1.42]	1.8
Common effect model	58			58			<u></u>	-0.24	[-0.61; 0.13]	33.4
Heterogeneity: $I^2 = 0\%$, $\tau^2 = 0.022$	0, p = 0).44								
Common effect model	210			162			<u> </u>	-0.35	[-0.56; -0.14]	100.0
Heterogeneity: $I^2 = 0\%$, $\tau^2 = 0$, $p_a =$	0.57									
Test for subgroup differences ²	- 0 5 4	16 - 4 /-	- 0.40							

613 614

Figure 7. Forest plot for anticipatory motion cues



Funnel Plot (anticipatory motion cues) of pseudo 95% confindence limits

616 Figure 8. Funnel plot for the test of publication bias regarding anticipatory motion cues

Study	Standardised Mean Difference	SMD	95%-CI	P-value	Tau2	Tau	12
Omitting Maculewicz and Larsson (202	1)	-0.29	[-0.51; -0.06]	0.01	0	0	0%
Omitting de Winkel et al. (2021)	·	-0.39	[-0.62; -0.17]	< 0.01	0	0	0%
Omitting Karjanto et al. (2018)		-0.32	[-0.54; -0.09]	< 0.01	0	0	0%
Omitting Li and Chen(2022)		-0.32	[-0.54] -0.09]	< 0.01	0	0	0%
Omitting Kuiper et al. (2020)		-0.35	[-0.57] -0.12]	< 0.01	0.0031	0.0555	0%
Omitting Hainich et al. (2021)		-0.33	[-0.55] -0.11]	< 0.01	0	0	0%
Omitting Hainich et al. (2021)		-0.38	[-0.60; -0.16]	< 0.01	0	0	0%
Omitting Mu et al.(2020)		-0.35	1-0.56: -0.131	< 0.01	< 0.0001	0.0003	0%
Omitting Yusof et al. (2020)		-0.35	1-0.57: -0.121	< 0.01	0.0031	0.0558	0%
Omitting Reuten et al.(2023)		-0.40	[-0.64; -0.16]	< 0.01	0	0	0%
Common effect model		-0.35	[-0.56; -0.13]	< 0.01	0	0	0%
	-0.6 -0.4 -0.2 0 0.2 0.4 0).6					

617 618

Figure 9. Influence analysis for anticipatory motion cues

619 3.2.3. A Comparison of The Effect of Cues on Motion Sickness Severity

To further quantify the influence of different cues on motion sickness severity, we performed a Q-test (Borenstein et al., 2021) to compare the effect sizes among natural present motion cues, artificial present motion cues, and artificial anticipatory motion cues. As shown in Table 10, it was found that the natural present motion cues were more effective in reducing motion sickness compared to other types of cues; whereas no difference was observed among other types of cues.

626

Table 10. Results of the Q-test

Types of motion cues	Natural present	Artificial present	Artificial anticipatory
	motion cues	motion cues	motion cues
			(non-visual)
Artificial present motion	Q(1) = 26.51	-	-
cues	<i>p</i> < 0.001		
Artificial anticipatory	Q(2) = 11.63	Q(1)=1.21	-
motion cues (non-visual)	<i>p</i> = .003	<i>p</i> = .3	
Artificial anticipatory	Q(2) = 10.4	Q(1) = .01	Q(1) = .5
motion cues (visual)	<i>p</i> = .006	<i>p</i> = .9	p = .5

627 **4. Discussion**

With the development of smart cockpits, more and more infotainment systems have been embedded into vehicles. The bring-in devices (e.g., smartphones and tablets) are also becoming increasingly prevalent in vehicles. This raises concerns about motion sickness or car sickness among occupants. Hence, we did a systematic review of experimental evidence of motion sickness inducers and a meta-analysis of inducers whose effectiveness is still inconclusive. In total, 57 studies were identified following the framework of PRISMA. In general, an increasing number of studies started to investigate the influential factors of motion sickness since 2014 (see Figure 10), potentially due to the rapid development of smart cockpits and the maturation of driving automation. Additionally, starting in 2014, researchers started to pay attention to the influence of internal layout and individual differences on motion sickness.





641

Figure 10. Identified studies on motion sickness in vehicles and the investigated inducers byyear (Note: the year 2023 was not included given only one study was identified in 2023).

Based on the results of the included studies, we categorized the inducers of motion sickness in vehicles into eight categories, i.e., eye view (which influences the availability of Natural present motion cues), NDRT availability, artificial motion cues, head dynamic movement, vehicle dynamics, internal layout, individual difference, and others. These 8 categories were further divided into 22 subgroups (see Figure 3). For example, the head dynamic movement can be further categorized into alignment with gravito-inertial force and tilt in cornering. 651 So far, the effects of providing motion cues have attracted the most attention from 652 researchers, followed by vehicle dynamics and eve view. Different perceptual channels have 653 been used to provide motion cues to occupants in previous research, including visual 654 information, tactile information, and auditory information. Inconsistent results have also been 655 identified regarding providing motion cues. Our meta-analysis provides insights into this 656 discrepancy. We found that in general the present motion cues and anticipatory motion cues 657 were effective in the mitigation of motion sickness. However, only non-visual artificial 658 anticipatory motion cues and natural present motion cues were effective; while neither 659 artificial present motion cues nor visual artificial anticipatory motion cues had effects on 660 mitigating motion sickness. It is possible that occupants' visual channel is more likely to be 661 occupied by other visual information in/outside vehicles; while the auditory/tactical 662 preemption effects (Smith et al., 2009; Wickens et al., 2005) may lead to better effects of 663 non-visual anticipatory cues. Further, the natural present motion cues were more effective in 664 mitigating motion sickness compared to both present and anticipatory artificial motion cues. 665 Further, though some artificial motion cues may alleviate motion sickness, the effect sizes of them are smaller than the natural present motion cues (e.g., non-visual anticipatory cues: 666 SMD = -0.41 vs. natural present motion cues: SMD = -0.85). However, this conclusion is 667 668 highly susceptible to the design of the HMIs that provide the artificial motion cues, which 669 should be investigated systematically.

As for vehicle dynamics, previous research investigated the influence of the oscillation/vibration on motion sickness, including the frequency, phase, amplitude, and the accumulation of acceleration in different directions. The driving style has also been considered. However, for some vehicle-dynamics-related inducers, the conclusion was still inconclusive. The findings regarding individual difference (specifically, the susceptibility to motion sickness) was also inconsistent. Despite the significant positive correlation between

susceptibility and motion sickness in most studies, one study (Kuiper et al., 2019) reported an
insignificant correlation. This insignificant result in Kuiper et al., (2019) could be attributed
to inadequate motion exposure, relatively small sample size, and relatively low mean or
variation of MSSQ compared to other studies that obtained significant results.

680 As for the eye view, it can be considered as being associated with motion cues. 681 Specifically, the blindfold view or internal view removes the motion cues to some extent 682 compared to the external view), which should lead to more server motion sickness compared 683 to the external view. However, inconsistent experimental evidence has been observed when 684 comparing the external view versus the blindfolded view. In the identified literature, 5 out of 685 6 identified experiments showed that the motion sickness with an external view was less 686 severe than that of a blindfold view, but 1 (out of 6) experiment showed a contradictory 687 result. This study was conducted in a driving simulator and hence the simulator sickness 688 induced by the virtual environment in the external view condition might explain this 689 contradictory result in the study. At the same time, according to the sensory conflict theory, 690 the internal view condition should cause more motion sickness than the blindfold view 691 condition. However, the validity of the sensory conflict theory seems to be correlated with the 692 phase difference between fore-and-aft and pitch oscillation: in the out-of-phase condition, the 693 motion sickness of the blindfold view was more severe than that of the internal view; while in 694 the in-phase condition, more server motion sickness was observed with internal view.

695 **5.** Future Work

Among the 57 studies identified in the literature review, passengers were the targeted occupants in 56 studies and only 4 studies investigated motion sickness in drivers. With a high level of driving automation, i.e., SAE Level 3 or higher (SAE International, 2021), however, drivers will be less aware of the vehicle motions and may even be allowed to engage in NDRTs in some conditions. Drivers may have different strategies in allocating

their visual attention between NDRTs and driving-related information on the road compared
to passengers. Thus, their susceptibility to motion sickness might still be different compared
to passengers. Even for SAE Level-2 driving automation (SAE International, 2021), the
drivers might be less aware of the future vehicle motion compared to drivers in traditional
vehicles. Thus, future research may need to pay more attention to the motion sickness of
drivers in vehicles with driving automation.

707 On the other hand, although previous research explored a wide variety of inducers of 708 motion sickness, little attention has been paid to the interaction effect of these inducers. In 709 other words, how the combination of different inducers may affect motion sickness is still 710 unclear. Actually, previous research has observed several interaction effects between the 711 inducers. For example, with the fore-and-aft oscillation (vehicle dynamics), the mis-712 /alignment of GIF (head dynamic movement) did not influence motion sickness (Brietzke et 713 al., 2021b); while when there was lateral acceleration, the motion sickness was more severe when the GIF was misaligned (Sugiura et al., 2019). A similar interaction effect between the 714 715 driving style and NDRTs engagement was also observed (Jones et al., 2019). In vehicles, 716 motion sickness is not solely affected by a single factor. Thus, quantifying the effects of 717 inducer combinations may better support the design of the vehicle in order to alleviate motion 718 sickness. For example, motion sickness can also be affected by the self-adaption capability 719 (Yunus et al., 2022) and individual differences (Turner & Griffin, 1999a). Thus, we should 720 take individual differences into consideration when designing the HMIs that remove the 721 motion sickness inducers.

Finally, with the rapid development of multimodal interaction in intelligent cockpits (MarketResearch, 2023), new in-vehicle HMI technologies have been adopted in vehicles in recent years (e.g., augmented reality, Ohlson, 2022), which may or may not introduce new

inducers of motion sickness. Research is needed to evaluate these HMIs from the motion-sickness-induction perspective of view.

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